

1. S9.6F Incremental Optical Encoder (Solid shaft)

1.1 Introduction:

This product is an ultra-miniature photoelectric encoder with solid shaft flange mounting and incremental pulse signal. It is suitable for micro-sized equipment and industrial automation fields with limited space.

1.2 Feature:

- Encoder external diameter $\varnothing 9.6\text{mm}$, thickness 16.9mm, diameter of shaft $\varnothing 3.0\text{mm}$;
- Flange installation;
- Adopt non-contact photoelectric principle;
- Electrical interface TTL differential signal;
- Resolution per turn up to 5120PPR.

1.3 Application:

Micro equipments, small instruments and other automation control fields.

1.4 Connection:

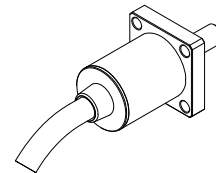
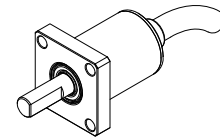
- Axial cable (standard length 0.5M)

1.5 Protection:

IP50

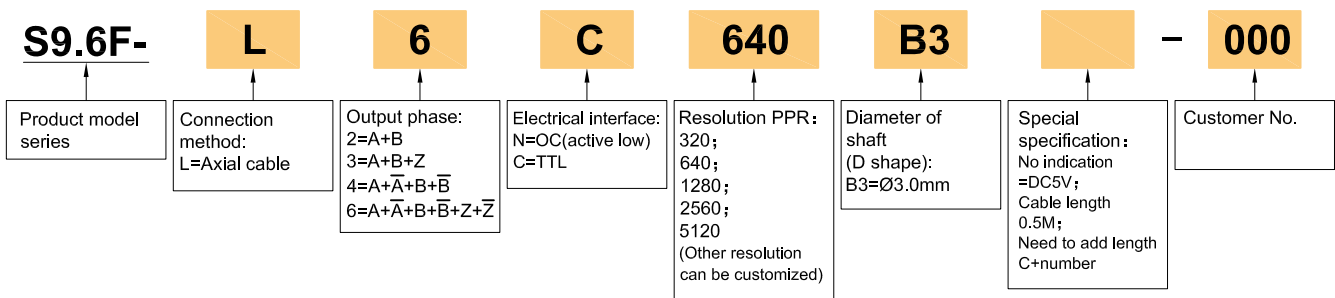
1.6 Weight:

About 15g



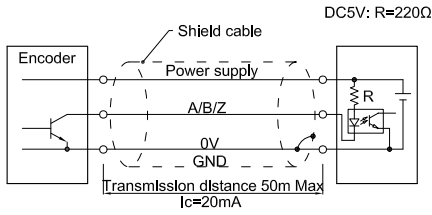
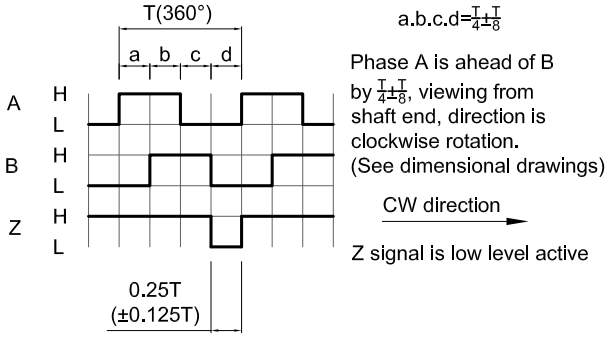
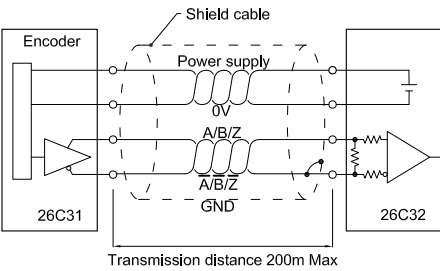
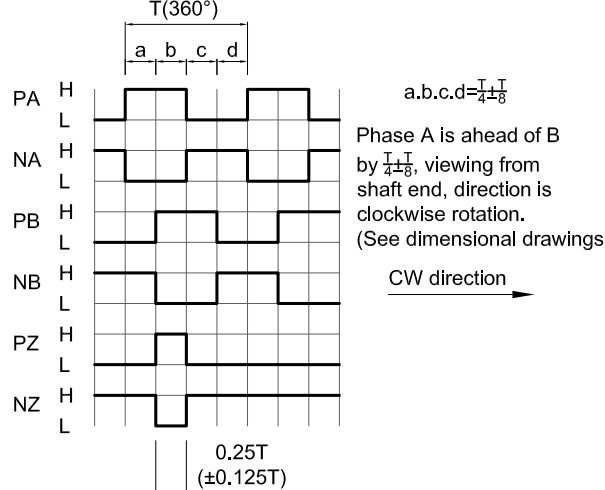
2. Model Selection Guide

Model composition(select parameters)



S9.6F INCREMENTAL

3. Output mode

Electrical interface	Output circuit	Output wave form
<p>OC NPN open collector circuit</p>		 <p>Phase A is ahead of B by $\frac{I \pm I}{4 \pm 8}$, viewing from shaft end, direction is clockwise rotation. (See dimensional drawings)</p> <p>CW direction →</p> <p>Z signal is low level active</p>
<p>TTL (DC5V)</p>		 <p>Phase A is ahead of B by $\frac{I \pm I}{4 \pm 8}$, viewing from shaft end, direction is clockwise rotation. (See dimensional drawings)</p> <p>CW direction →</p>

4. Electrical Parameters

Parameter		Output type		OC	TTL
Item					
Supply voltage		DC+5V±5%			
Consumption current		100mA Max			
Allowable ripple		≤3%rms			
Top response frequency		100KHz		200KHz	
Output capacity	Output current	Input	≤30mA	≤±20mA	
		Output	—		
	Output voltage	“H”	—	≥2.5V	
		“L”	≤0.4V	≤0.5V	
Load voltage		≤DC30V		—	
Rise & Fall time		Less than 2us(cable length: 2m)		≤100ns Less than 1us(Cable length: 2m)	
Mark to space ratio		45% to 55%			
Phase shift between A & B		90°±10° (frequency in low speed)			
		90°±20° (frequency in high speed)			
GND		Not connect to encoder			

5. Mechanical Specifications

Diameter of shaft	Ø3mm(D shape)
Starting torque	Less than $5 \times 10^{-4} \text{N} \cdot \text{m}$
Inertia moment	Less than $0.3 \times 10^{-6} \text{kg} \cdot \text{m}^2$
Shaft load	Radial 2N; Axial 2N
Slew speed	≤5000 rpm
Shell	Aluminium alloy
Weight	about 15g

6. Environmental Parameters





Environmental temperature	Operating: -20~+80°C; Storage: -25~+85°C
Environmental humidity	Operating and storage: 35~85%RH(noncondensing)
Vibration(Endurance)	Amplitude 0.75mm,5~50Hz,2h for X,Y,Z direction individually
Shock(Endurance)	49m/s ² 11ms three times for X,Y,Z direction individually
Protection	IP50

7. Wiring Table

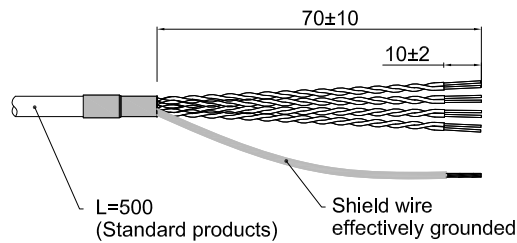
7.1 OC (Wiring table)

	Supply voltage		Incremental signal		
Wire color	Red	Black	White	Green	Yellow
Function	Up	0V	A	B	Z

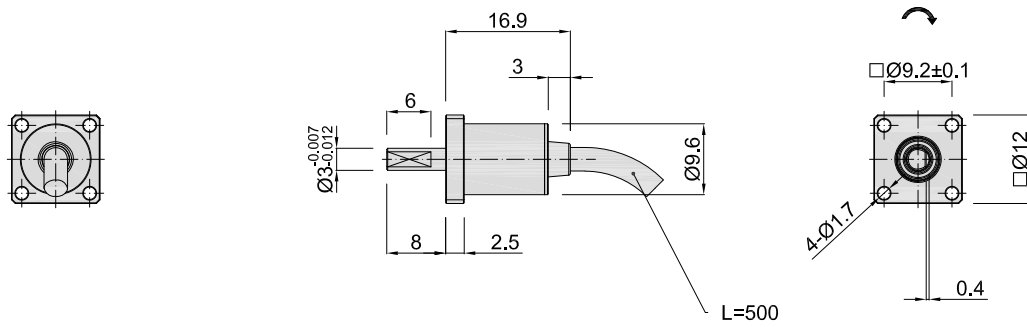
7.2 TTL (Wiring table)

	Supply voltage		Incremental signal					
Wire color	Red	Black	White	White/BK	Green	Green/BK	Yellow	Yellow/BK
Function	Up	0V	A+	A-	B+	B-	Z+	Z-
Twisted-paired cable								

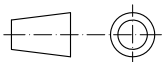
Up=Supply voltage.
Shield wire is not connected to the internal circuit of encoder.



8. Basic Dimensions



Unit: mm



↻ = Shaft rotation direction of the incremental signal output